

## COURSE DESCRIPTION – ACADEMIC YEAR 2024/2025

<b>Course title</b>	Modern Control
<b>Course code</b>	42412
<b>Scientific sector</b>	IINF-04/A
<b>Degree</b>	Bachelor in Electronics and Cyber-Physical Systems Engineering
<b>Semester</b>	II
<b>Year</b>	3
<b>Academic Year</b>	2024/25
<b>Credits</b>	9
<b>Modular</b>	no

<b>Total lecturing hours</b>	36
<b>Total lab hours</b>	54
<b>Attendance</b>	Attendance at lectures is strongly recommended. Attendance at exercise sessions is required.
<b>Prerequisites</b>	Lectures and exercises of Mathematical Analysis I and II; Linear Algebra; Physics I; Physics II; and Fundamentals of Systems and Control
<b>Course page</b>	

<b>Specific educational objectives</b>	The student should understand the basic principles of methods of modern control with focus on state-space control and optimal control and be able to apply them in exercises, including in Matlab and Simulink, as well as in laboratory experiments on real hardware.
--	--

<b>Lecturer</b>	<p>Prof. Karl von Ellenrieder - Facoltà di Ingegneria            Tel. : +39 0471 017172            E-mail: <a href="mailto:karl.vonellenrieder@unibz.it">karl.vonellenrieder@unibz.it</a>            Web: <a href="https://www.unibz.it/faculties/person/37038-karl-dietrich-von-ellenrieder">https://www.unibz.it/faculties/person/37038-karl-dietrich-von-ellenrieder</a></p> <p>Prof. Santos Miguel Orozco Soto - Facoltà di Ingegneria            Tel. : +39            E-mail:            Web:</p>
<b>Scientific sector of the lecturer</b>	IINF-04/A – Systems and Control Engineering
<b>Teaching language</b>	English
<b>Office hours</b>	As listed on Teams or by appointment
<b>Teaching assistant (if any)</b>	TBD
<b>Office hours</b>	As listed on Teams or by appointment

<p><b>List of topics covered</b></p>	<ol style="list-style-type: none"> <li>1. Modelling and systems analysis in state space (dynamic system modelling in time domain and state-space representation).</li> <li>2. Dynamic system response derived from state-space representation and steady-state error.</li> <li>3. Stability in state space.</li> <li>4. Control design in state space (Pole placement design techniques; controllability, observability, full-state observers).</li> <li>5. Optimal control of dynamic systems (Problems with fixed and variable end-points as well as with equality and inequality constraints; maximum principle and Hamilton-Jacobi-Bellmann equation; linear quadratic regulator).</li> <li>6. Understanding of observers in control systems.</li> <li>7. Understanding of optimal state observers and Kalman filters.</li> <li>8. Computer-aided analysis and design using Matlab/Simulink.</li> <li>9. Implementation of controllers and experimental evaluation on real-hardware setups.</li> </ol>
<p><b>Teaching format</b></p>	<p>Lessons are divided into i) theoretical classroom lessons, ii) classroom exercises, and iii) lab exercises.</p>

<p><b>Learning outcomes (ILOs)</b></p>	<p><u>Knowledge and understanding</u>        Knowledge and understanding in the field of:</p> <ol style="list-style-type: none"> <li>1. State-space modelling and control</li> <li>2. Optimal control</li> <li>3. Observers</li> </ol> <p><u>Applying knowledge and understanding</u></p> <ol style="list-style-type: none"> <li>4. Ability to apply knowledge for solving given problems, including solving them with numerical data using software packages like Matlab/Simulink and their implementation and evaluation on real hardware setups.</li> </ol> <p><u>Making judgements</u></p> <ol style="list-style-type: none"> <li>5. Ability to judge plausibility of results.</li> </ol> <p><u>Communication skills</u></p> <ol style="list-style-type: none"> <li>6. In-class exercises will require you justify your solutions/conclusions concisely (in clear and simple language).</li> </ol> <p><u>Ability to learn</u></p> <ol style="list-style-type: none"> <li>7. Learning skills to independently study and apply methods of modern control for specific applications beyond topics covered in this lecture.</li> </ol>
--	--

<p><b>Assessment</b></p>	<p><b>Formative assessment</b></p> <table border="1" data-bbox="641 472 1402 618"> <thead> <tr> <th>Form</th> <th>%</th> <th>Length /duration</th> <th>ILOs assessed</th> </tr> </thead> <tbody> <tr> <td>Exercises</td> <td>40</td> <td>54 hours total (lab + in class)</td> <td>1-7</td> </tr> </tbody> </table> <p><b>Summative assessment</b></p> <table border="1" data-bbox="641 725 1402 831"> <thead> <tr> <th>Form</th> <th>%</th> <th>Length /duration</th> <th>ILOs assessed</th> </tr> </thead> <tbody> <tr> <td>Final Exam</td> <td>60</td> <td>4 hours</td> <td>1-7</td> </tr> </tbody> </table>	Form	%	Length /duration	ILOs assessed	Exercises	40	54 hours total (lab + in class)	1-7	Form	%	Length /duration	ILOs assessed	Final Exam	60	4 hours	1-7
Form	%	Length /duration	ILOs assessed														
Exercises	40	54 hours total (lab + in class)	1-7														
Form	%	Length /duration	ILOs assessed														
Final Exam	60	4 hours	1-7														
<p><b>Assessment language</b> <b>Evaluation criteria and criteria for awarding marks</b></p>	<p>English</p> <p>Labs: Completeness and correctness of reports; quality of writing; level of observation of physical processes</p> <p>In-Class Exercises: Completeness and correctness of answers; level of understanding</p> <p>Written Final Exam: Completeness and correctness of answers.</p> <p>Students must receive an overall grade of greater than 60/100 points to pass the course.</p>																
<p><b>Required readings</b> <b>Supplementary readings</b></p>	<p>Lecture notes provided</p> <p>Additional books and articles may be recommended by the instructor during the course.</p>																