

## Syllabus Course description

Course title	Functional Mechanical Design
Course code	47563
Scientific sector	ING-IND/13
Degree	Master Industrial Mechanical Engineering
Semester	1
Year	1
Academic year	2024-2025
Credits	5
Modular	No

Total lecturing hours	28
Total lab hours	0
Total exercise hours	18
Attendance	Strongly recommended
Prerequisites	None.
Course page	https://www.unibz.it/en/faculties/engineering/master-
	industrial-mechanical-engineering/course-
	offering/?academicYear=2024

Specific objectives	The course aims at giving the guidelines for the functional design of automatic machines, in particular taking into
	account mechanical efficiency.
	Criteria and methods to analyze and choose mechanical
	devices, design motion laws and to evaluate the best
	system to minimize the energy dissipation in
	electromechanical systems will be addressed.

Lecturer	Dr. Roberto Belotti		
Scientific sector of the lecturer	ING-IND/13		
Teaching language	English		
Office hours	See timetable online: <a href="http://www.unibz.it/en/timetable/">www.unibz.it/en/timetable/</a> and by appointment		
Teaching assistant (if any )	N.A.		
Office hours of teaching assistant	N.A.		
List of topics covered	<ul> <li>Introduction to functional design, classification of the mechanisms and motion systems.</li> <li>Basic concepts and definitions. Mechanical efficiency, performance, energy efficiency and energy savings in automatic machines. Direct/reverse energy flow and motor–load</li> </ul>		



Freie Universität Bozen Unibz Libera Università di Bolzano Università Liedia de Bulsan

	<ul> <li>systems.</li> <li>Mechanical components for transferring and transforming energy. Classification based on function, working principle as well as performance and efficiency.</li> <li>Optimization aimed at improving the quality of motion and efficiency.</li> <li>Energy storage systems and energy recovery. Classification (working principle and scope of use).</li> <li>Classification of motion laws implemented in automatic machines. Analysis of the main requirements in the design of a motion law and its optimization.</li> </ul>
Teaching format	Frontal lectures, hand-calculation exercises, computer- assisted exercises

Learning outcomes	<ul> <li>I. Knowled</li> <li>Identisystem</li> <li>Under</li> </ul>	<b>Ige and Understanding</b> tify the main components of tra ems and sources of inefficiency erstand the basic principles of er	nsmission nergy storage,
	<ul> <li>Applying</li> <li>Evalution</li> <li>Evalution&lt;</li></ul>	<b>g knowledge and understand</b> uate and select the proper trans em considering mechanical and o ency;	<b>ling</b> mission energy
	<ol> <li>Making : <ul> <li>Select differ</li> <li>Choor elect trans</li> </ul> </li> <li>4. Community <ul> <li>Ability technistic</li> <li>Learning</li> <li>Ability acquure docuure</li> </ul> </li> </ol>	judgments ct and design an effective motio rent working conditions and targo ose suitable combination of mech ric components for energy trans ofer <b>nication skills</b> by to structure and prepare scier <b>nical</b> documentation <b>g skills</b> by to independently build upon t ired during the study course by erstanding scientific and technication.	n law under gets; hanical and sformation and ntific and he knowledge reading and al
Assessment	Formative	assessment	
	Form	Details	Learning outcomes assessed
	In-class exercises	Continuously in exercise courses	1, 2, 3, 4, 5
	Summative	e assessment	



	Form	Duration	Learning outcomes assessed	
	Written exam	3 h	1, 2, 3, 4, 5	
Assessment language	English			
Evaluation criteria and criteria for awarding marks	The written examination will include both theoretical questions and numerical exercises to show ability to solv problems handled in this course.			
	Form	Evaluation	criteria and weight	
	Written examinatio	n Theoretical Correctness Correctness Appropriate	Theoretical knowledge (35%) Correctness of methods (30%) Correctness in solution (30%) Appropriate use of units (5%)	

Required readings	Slides provided to the students after each lecture and notes taken by students during lecture
Supplementary readings	<ul> <li>A collection of suggested readings from various sources will be announced during the course. Such sources will be papers, manuals, technical notes, and excerpts from textbooks, including <ul> <li>Biagiotti, Luigi, and Claudio Melchiorri.</li> <li><i>Trajectory planning for automatic machines and robots</i>. Springer Science &amp; Business Media, 2008.</li> <li>Norton, Robert L. <i>Kinematics and dynamics of machinery</i>. McGraw Hill Higher Education, 2009.</li> <li>Filizadeh, S. <i>Electric Machines and Drives: Principles, control, modelling and simulation</i>. CRC Press, 2013.</li> </ul> </li> </ul>