

## **COURSE DESCRIPTION – ACADEMIC YEAR 2023/2024**

Course title	Modeling and Simulation of Multibody Systems with Multiphysics Coupling		
Course code			
Scientific sector	ING-IND/13 + ING-IND/14		
Degree	PhD in Advanced Systems Engineering		
Semester	2		
Year	2023-2024		
Credits	3		
Modular			
L			
Total lecturing hours	24 Attendance to the lectures is highly recommended. Non-attending students have to contact the lecturer at the start of the course to agree on the modalities of the independent study.		
Attendance			
	For the hands-on sessions and case-study/project activities, attendance is compulsory.		
Prerequisites			
Specific educational objectives	<ul> <li>This course aims at touching fundamental and advanced concepts on the:</li> <li>A. modeling and simulation of complex articulated mechanical systems, denoted as multibody systems, such as vehicles, robots, mechanical transmissions, etc., also featuring a multiphysics coupling.</li> <li>B. various modelling approaches available to simulate multiphysical engineering systems. Interactions between solids and between solids &amp; fluids will be covered both from a theoretical and from a practical point of view.</li> <li>Hands-on sessions will allow students to implement and evaluate case-studies and examples.</li> </ul>		

Lecturer(s)	Renato Vidoni <u>https://www.unibz.it/it/faculties/engineering/academic-</u> <u>staff/person/31254-renato-vidoni</u>
	Franco Concli https://www.unibz.it/it/faculties/engineering/academic- staff/person/34279-franco-concli
	<i>Veit Gufler <u>https://www.unibz.it/en/faculties/engineering/academic-</u> <u>staff/person/38756-veit-gufler</u></i>
Contact	<i>RV and VG: L6.05, FC: L4.04 {renato.vidoni; franco.concli; veit.gufler}@unibz.it</i>



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Scientific sector of	ING-IND/13		
lecturer(s)	ING-IND/14		
Teaching language	English		
Office hours	Arrange beforehand by email.		
Lecturing Assistant (if any)			
Contact LA			
List of topics	<ul> <li>This course is subdivided into two modules aimed at touching fundamental and advanced concepts on the: <ul> <li>a) Modeling and simulation of complex multibody systems (MBS).</li> <li>b) Approaches available to simulate multi-physical engineering systems.</li> </ul> </li> <li>Topics: <ul> <li>a) Introduction and reference kinematics for MBS; analytical techniques; equations of motion; mechanics of deformable bodies (small and large deformations); Floating Frame of Reference formulation or Equivalent Rigid Link System formulation; hints on Model Order Reduction.</li> <li>b) Grid-based (Finite Volumes - FV - and Finite Elements – FE) and meshless (Smooth Particle Hydrodynamics - SPH) modelling approaches; strong and weak couplings between different physics (mesh-based approaches – i.e FV &amp; FV and FV &amp; FE). SPH theory and application.</li> </ul> </li> </ul>		
	OpenFOAM®, Calculix, DualSPHysics) and commercial software (e.g. Adams MSC) will be uses.		
Teaching format	Frontal lectures, exercises, project(s).		
Learning outcomes	By the end of the course, students should be able to: <u>Knowledge and understanding</u> D1.1) Know the theoretical bases of the available numerical simulations techniques for the solution of engineering problems (M1 & M2). <u>Applying knowledge and understanding</u> D2.1) Know how to apply modelling techniques for multibody systems (M1). D2.2) Know how to apply numerical approaches to practical design cases of multiphysical environments (M2). <u>Making judgements</u> D3.1) Critically analyze the results of the simulations, discuss their accuracy, on the basis of the modelling approach (M1 & M2). D3.2) Define the best modelling approach with a tradeoff between the accuracy and the computational effort (M1 & M2). <u>Communication skills</u> D4.1) Prepare a technical report/paper and a presentation describing the selected topic/ application where the methods, developed activity and choices are presented and discussed (M1 & M2). <u>Learning skills</u> D5.1) Ability to autonomously extend the knowledge acquired (M1 & M2).		



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Assessment	Formative assessment		
	Form In class exercises	Length /duration 8 X 120 minutes	ILOs assessec 2, 3, 4
	Summative assessment		
	Form assessed	%	ILOs
	Report and presenta	ation* 100	2,3,4,5
Assessment language	English		
Assessment Typology			
Evaluation criteria and criteria for awarding marks	Quality of the technical report (40%), correctness of the results (30%) Presentation (30%)		
Required readings	Lecture notes and d	ocuments for exercise will h	a available on OI F

Required readings	Lecture notes and documents for exercise will be available on OLE.	
Supplementary readings	Further material will be possibly provided by the lecturers	
Software used	Python, OpenFOAM®, Calculix, DualSPHysics, Adams MSC, Matlab, PrePoMax	