

Syllabus Course description

Course title	Automatic Control
Course code	47511
Scientific sector	ING-INF/04
Degree	Master in Industrial Mechanical Engineering
Semester	Ι
Year	Ι
Academic Year	2020-2021
Credits	5
Modular	No

Total lecturing hours	28 hrs		
Total exercise hours	20 hrs		
Attendance	Attendance at lectures is strongly recommended. Attendance at exercise sessions is required.		
Prerequisites	none		
Course page	https://www.unibz.it/en/faculties/sciencetechnology/mas ter-industrial-mechanical-engineering/course- offering/?academicYear=2020		

Specific educational objectives	The course provides an introduction to the fundamentals of control theory, at an introductory/intermediate level.
objectives	
	Topics covered include: Laplace Transform, Root Locus,
	Frequency Design Methods and State Space Techniques
	(time permitting). The course is aimed at beginning
	graduate students and focuses on building understanding
	and intuition. Examples and exercises that use Matlab and
	Simulink will be given.

Lecturer	Prof. Karl von Ellenrieder Facoltà di Scienze e Tecnologie Building K, Room 2.08 Tel.: +39 0471 017172 E-mail: <u>karl.vonellenrieder@unibz.it</u> Web: <u>https://www.unibz.it/en/faculties/sciencetechnology/phd-in-food-engineering-and-biotechnology/phd-students-feb/person/37038-karl-dietrich-von-ellenrieder</u>		
Scientific sector of the lecturer	ING-INF/04 - Automatica		
Teaching language	English		
Office hours	As listed on Cockpit or by appointment		
Teaching assistant (if any)	N/A		
Office hours	As listed on Cockpit or by appointment		
List of topics covered	The course covers the following topics: 1. Introduction		



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	a. Block diagrams			
	b. Linear stability			
	c. Effects of feedback on stability			
	2. Classical Control			
	a. root locus – fundamental ideas and design			
	approach			
	 b. frequency methods – fundamental ideas and 			
	design approach			
	3. State Space Control			
Teaching format	Classroom lectures and exercises			
Learning outcomes (ILOs)	Knowledge and understanding			
	1. Applying basic feedback principles to a broad range of			
	dynamic system models (such as those typically			
	learned in the 1 st cycle).			
	2. Defining feedback loop requirements for improving			
	system steady state response.			
	3. Understanding conditions that guarantee closed loop			
	system stability.			
	4. How to design controllers via Root Locus, Frequency			
	Response and State Space Techniques.			
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	Applying knowledge and understanding			
	Applying knowledge and understanding			
	C Applying developing and presenting control pretoned			
	5. Analyzing, developing and presenting control systems			
	for applications that span multiple disciplines through			
	exercises, which complement the lectures.			
	Making judgements			
	6. On the choice of analytical and numerical tools to use			
	in the exercises. This may require you to integrate			
	knowledge, handle complexity, and formulate			
	judgements with incomplete data.			
	Communication skills			
	7. In-class exercises will require you justify your			
	solutions/conclusions concisely (in clear and simple			
	language).			
	Learning Skills			
	9 Students will be required to develop a proficiency in			
	8. Students will be required to develop a proficiency in			
	Matlab and Simulink with a few in-class examples, but			
	mostly on their own. This is intended to help students			
	develop the ability to study in a manner that is largely			
	self-directed or autonomous.			



Assessment	Formative assessment			
	Form	Length /duration		ILOs assessed
	Exercises 20 hours total		1-8	
	Summative assessment			
	Form	%	Length /duration	ILOs assessed
	Exercises	15		1-8
	Final Exam	85	4 hours	1-6
Assessment language	English			
Evaluation criteria and criteria for awarding marks	In-Class Exercises: Completeness and correctness o answers; level of understanding			correctness of
Written Final Exam: Completeness and answers.				d correctness of
	overall grade of ss the course.			
Required readings	Lecture notes	and exe	rcises will be availa	ble on the UniB7

Required readings	Lecture notes and exercises will be available on the UniBZ Open Learning Environment (OLE)
Supplementary readings	Additional books and articles may be recommended by the instructor during the course.