

Syllabus Course description

Course title	Automatic Control				
Course code	47511				
Scientific sector	ING-INF/04				
Degree	Master in Industrial Mechanical Engineering				
Semester	1				
Year	I				
Academic Year	2018-2019				
Credits	5				
Modular	no				
Total lecturing hours	28 hrs				
Total exercise hours	20 hrs				
Attendance	Attendance at lectures is strongly recommended. Attendance at exercise sessions is required.				
Prerequisites	none				
Course page	http://www.unibz.it/en/sciencetechnology/progs/master/ industrial-and-mechanical-engineering/default.html				
Specific educational	The course provides an introduction to the fundamentals				
objectives	of control theory, at an introductory/intermediate level. Topics covered include: Laplace Transform, Root Locus, Frequency Design Methods and State Space Techniques (time permitting). The course is aimed at beginning graduate students and focuses on building understanding and intuition. Examples and exercises that use Matlab and Simulink will be given.				
Lecturer	Prof. Karl von Ellenrieder Facoltà di Scienze e Tecnologie Building K, Room 2.08 Tel.: +39 0471 017172				
	E-mail: karl.vonellenrieder@unibz.it Web : https://next.unibz.it/en/faculties/sciencetechnology/ academic-staff/person/37038-karl-dietrich-von-ellenrieder				
Scientific sector of the lecturer	ING-INF/04 - Automatica				
Teaching language	English				
Office hours	As listed on Cockpit or by appointment				
Teaching assistant (if any)					
Office hours	As listed on Cockpit or by appointment				
List of topics covered	The course covers the following topics: 1. Introduction a. Block diagrams b. Linear stability c. Effects of feedback on stability				



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	2. Classical Control				
	a. root locus – fundamental ideas and design				
	approach				
	b. frequency methods – fundamental ideas and				
	design approach				
	3. State Space Control				
Teaching format	Classroom lectures and exercises				
Learning outcomes (ILOs)	Knowledge and understanding				
Curcomes ()	Thomeage and understanding				
	1. Applying basic feedback principles to a broad range of				
	dynamic system models (such as those typically learned in the 1 st cycle).				
	 Defining feedback loop requirements for improving system steady state response. 				
	3. Understanding conditions that guarantee closed loop				
	system stability.				
	4. How to design controllers via Root Locus, Frequency				
	Response and State Space Techniques.				
	Applying knowledge and understanding				
	5. Analyzing, developing and presenting control systems				
	for applications that span multiple disciplines through				
	exercises, which complement the lectures.				
	Making judgements				
	6 On the choice of analytical and numerical tools to use				
	6. On the choice of analytical and numerical tools to use in the exercises. This may require you to integrate				
	knowledge, handle complexity, and formulate				
	judgements with incomplete data.				
	Communication skills				
	7. In-class exercises will require you justify your				
	solutions/conclusions concisely (in clear and simple				
	language).				
	Learning Skills				
	8. Students will be required to develop a proficiency in				
	Matlab and Simulink with a few in-class examples, but				
	mostly on their own. This is intended to help students				
	develop the ability to study in a manner that is largely				
	self-directed or autonomous.				



Assessment	Formative assessment			
	Form	Length /duration20 hours total		ILOs assessed 1-8
	Exercises			
	Summative assessment			
	Form	%	Length /duration	ILOs assessed
	Exercises	15		1-8
	Final Exam	85	4 hours	1-6
Assessment language	English			
Evaluation criteria and criteria for awarding marks	In-Class Exercises: Completeness and correctness of answers; level of understanding			
	Written Final Exam: Completeness and correctness of answers.			
	Students are required to receive an overall grade of greater than 60/100 points in order to pass the course.			
Required readings	Lecture notes and exercises will be available on the UniB2			

Required readings	Lecture notes and exercises will be available on the UniBZ Open Learning Environment (OLE)		
Supplementary readings	Additional books and articles may be recommended by		
	the instructor during the course.		